

# Friction Stir Welding Control: Feasibility Study

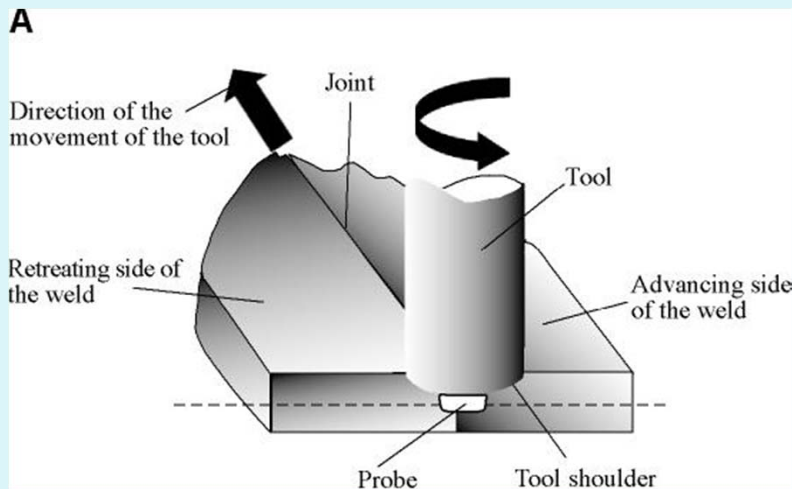
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# Friction Stir Welding Control Overview

- ◆ Friction Stir welding is a solid state metal joining process
- ◆ A rotating tool creates heat and plasticizes the metal. This allows the metal to be “stirred” around.



# Friction Stir Welding Applications



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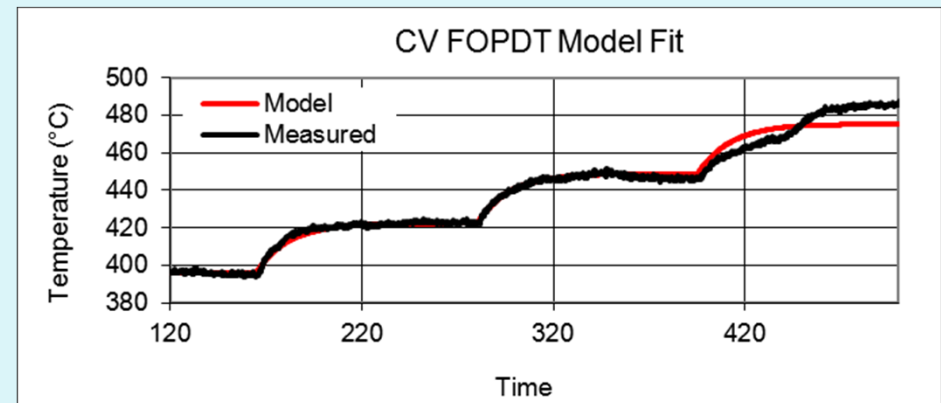
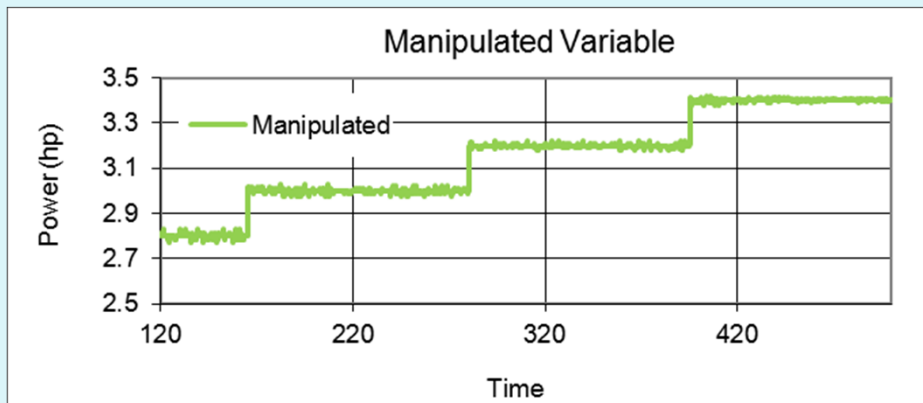
# Feasibility Study Objectives

- ◆ Develop Simplified Model of FSW Process
  - ◆ PDE of Tool Heat Transfer
- ◆ Investigate feasibility of FSW model-based control
  - ◆ 2-3 weeks of effort
  - ◆ Explore feasibility through simulation
  - ◆ Compare model to run data
  - ◆ Demonstrate in simulation
    - ◆ PID (Proportional Integral Derivative Control)
    - ◆ MPC (Model Predictive Control)
  - ◆ Detail projected effort / costs to implement MPC
  - ◆ Develop implementation plan



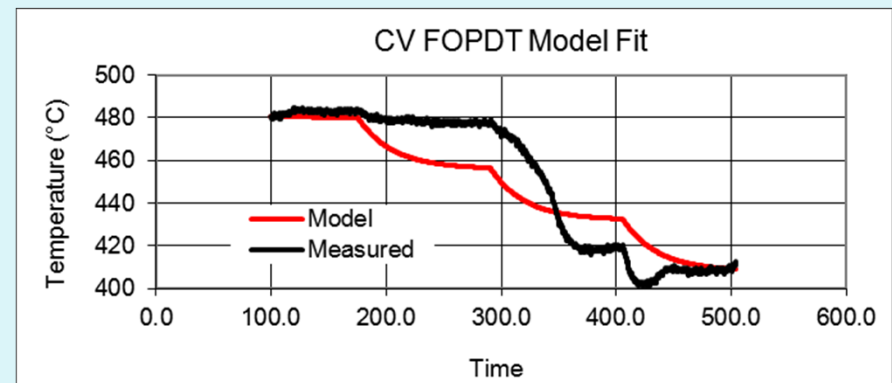
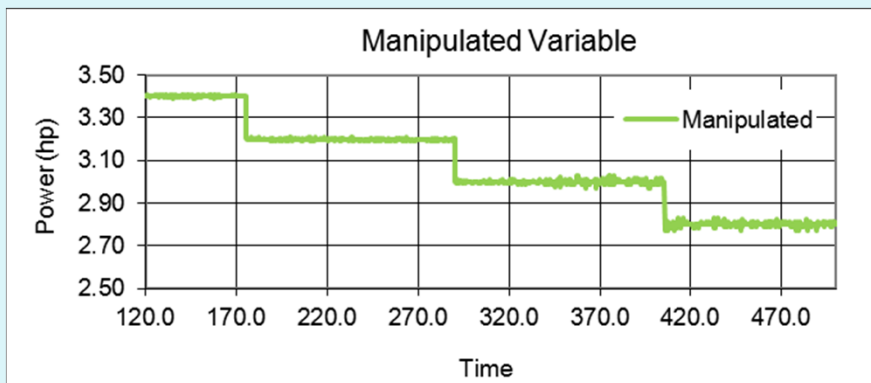
# FSW Process Model - FOPDT

- ◆ Model #1 of FSW Process – Step Up in Power
  - ◆ First Order Plus Dead-Time (FOPDT) Model
  - ◆ Model predictions on same Aluminum data
  - ◆ Gain ( $K_p$ ): 131.7 °C/hp
  - ◆ Time Constant ( $\tau_p$ ): 16.5 sec
  - ◆ Dead-time ( $\theta_p$ ): 1 sec



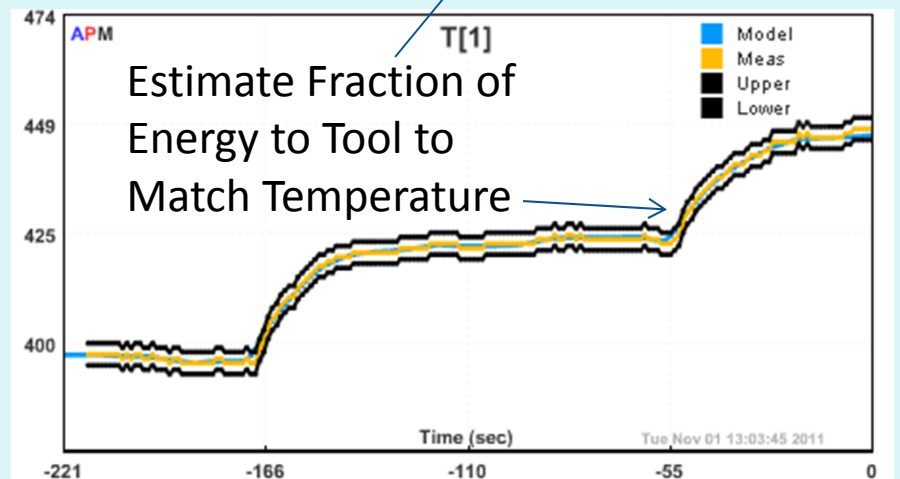
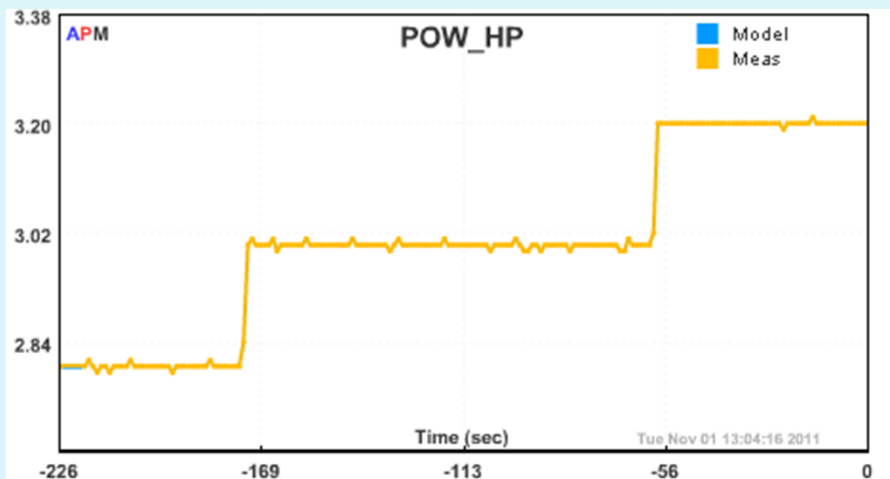
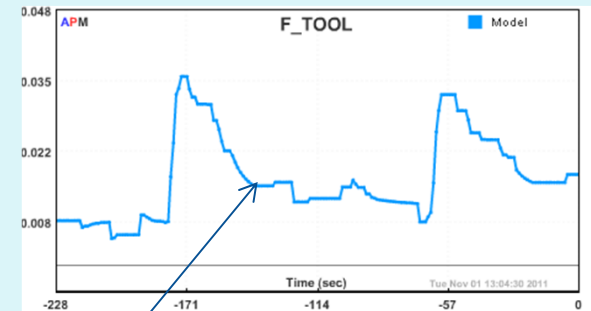
# FSW Process Model - FOPDT

- ◆ Model #1 of FSW Process – Step Down in Power
  - ◆ First Order Plus Dead-Time (FOPDT) Model
  - ◆ Model predictions on same Aluminum data
  - ◆ Gain ( $K_p$ ): 120 °C/hp
  - ◆ Time Constant ( $\tau_p$ ): 20-30 sec
  - ◆ Dead-time ( $\theta_p$ ): 1 sec



# FSW Process Model – PDE Model

- ◆ Model #2 of FSW Process
  - ◆ PDE of Tool Heat Transfer
  - ◆ Demonstrate model predictions on Aluminum
  - ◆ Fit PDE model to process data



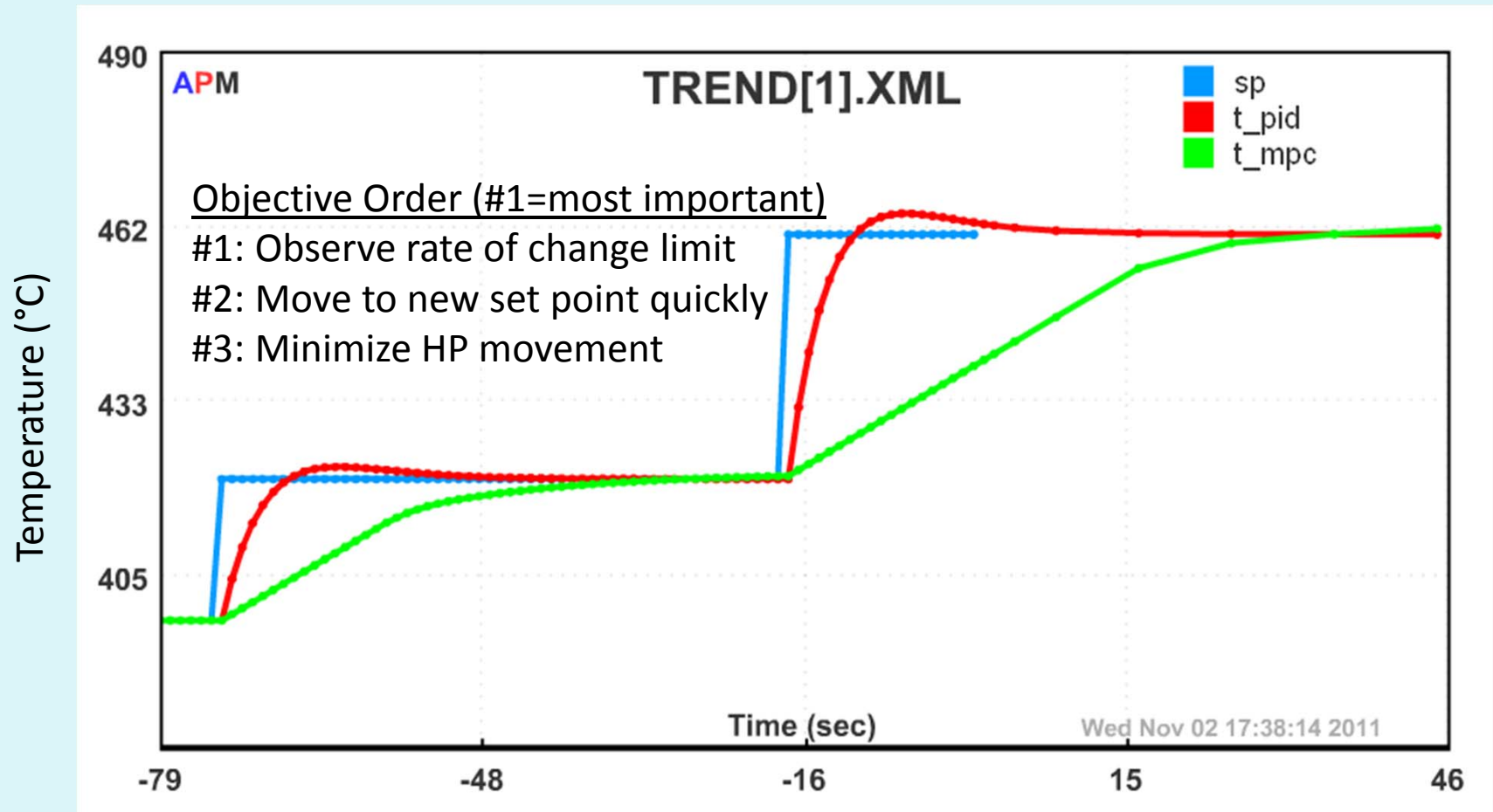
# FSW Temperature Control

- ◆ Current Practice
  - ◆ PID Control
  - ◆ Start-up procedure
    - ◆ Constant rotational speed
    - ◆ Manual adjustments to guide temperature
      - ◆ Z Axis Force
- ◆ Proposed Control Strategy
  - ◆ Model based control
  - ◆ Automatic control through start-up
    - ◆ Limit overshoot
    - ◆ Keep process within constraints
      - ◆ Rate of change limits for motor power (HP)
      - ◆ Rate of change limits for tip temperature

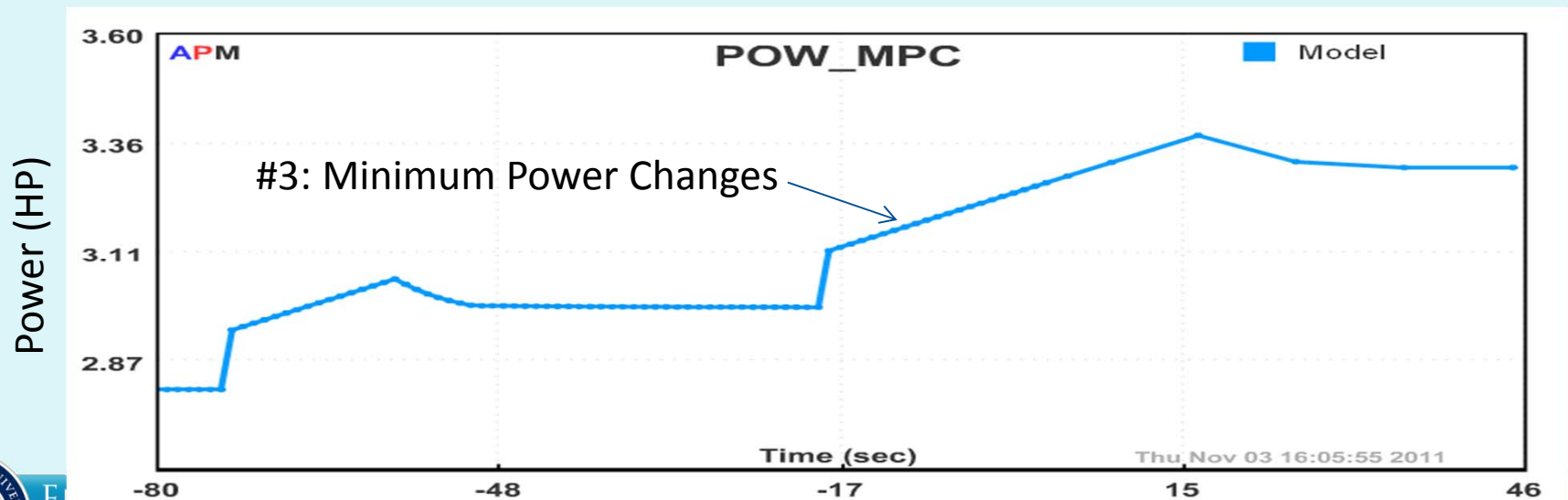
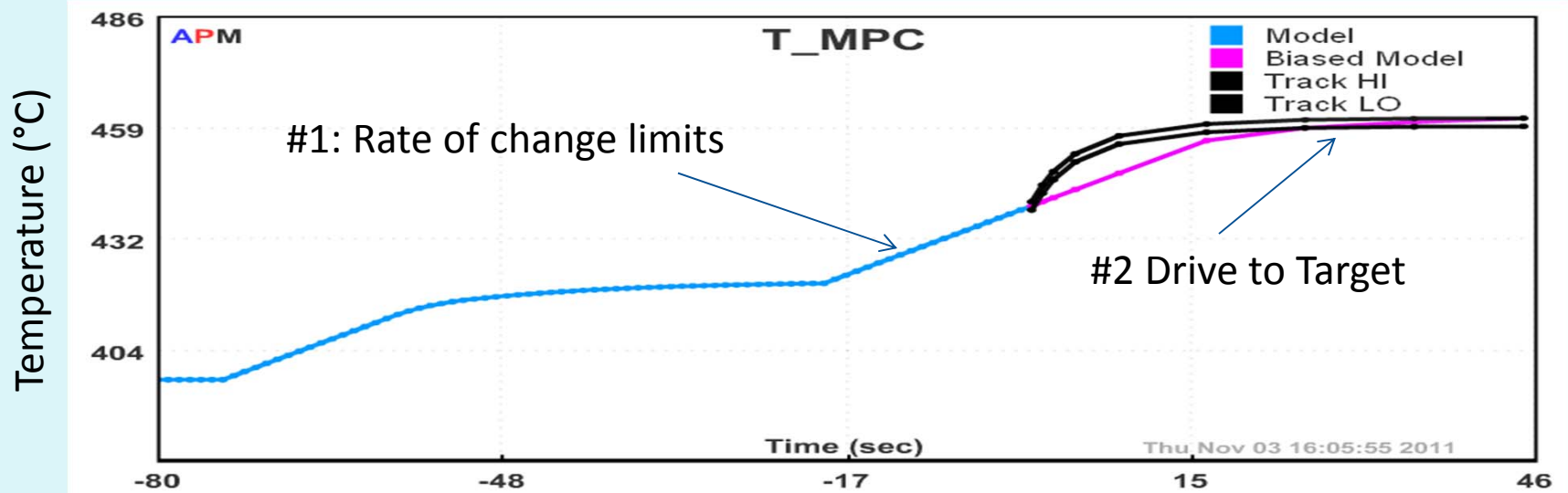




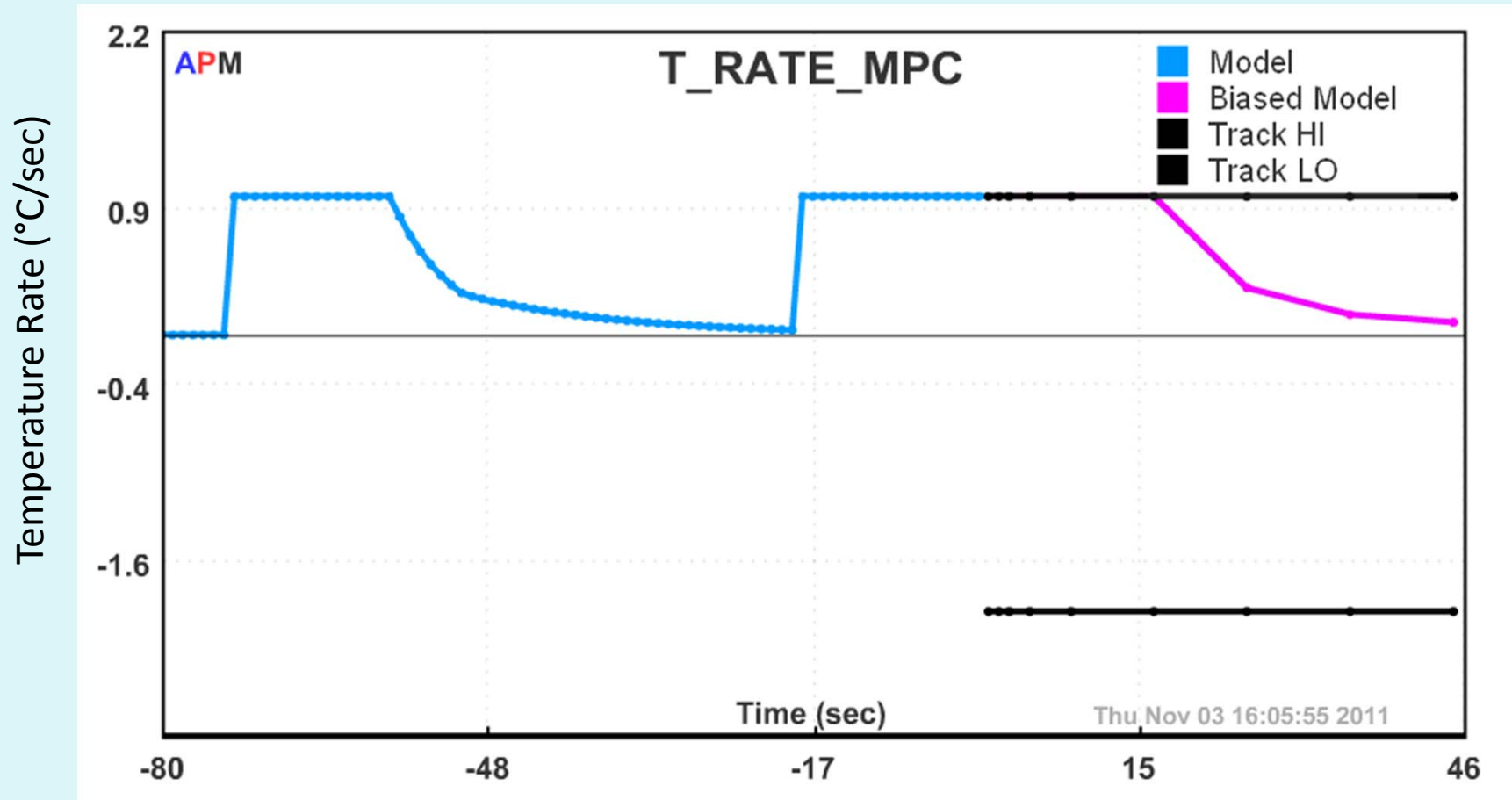
# Comparing PID and MPC



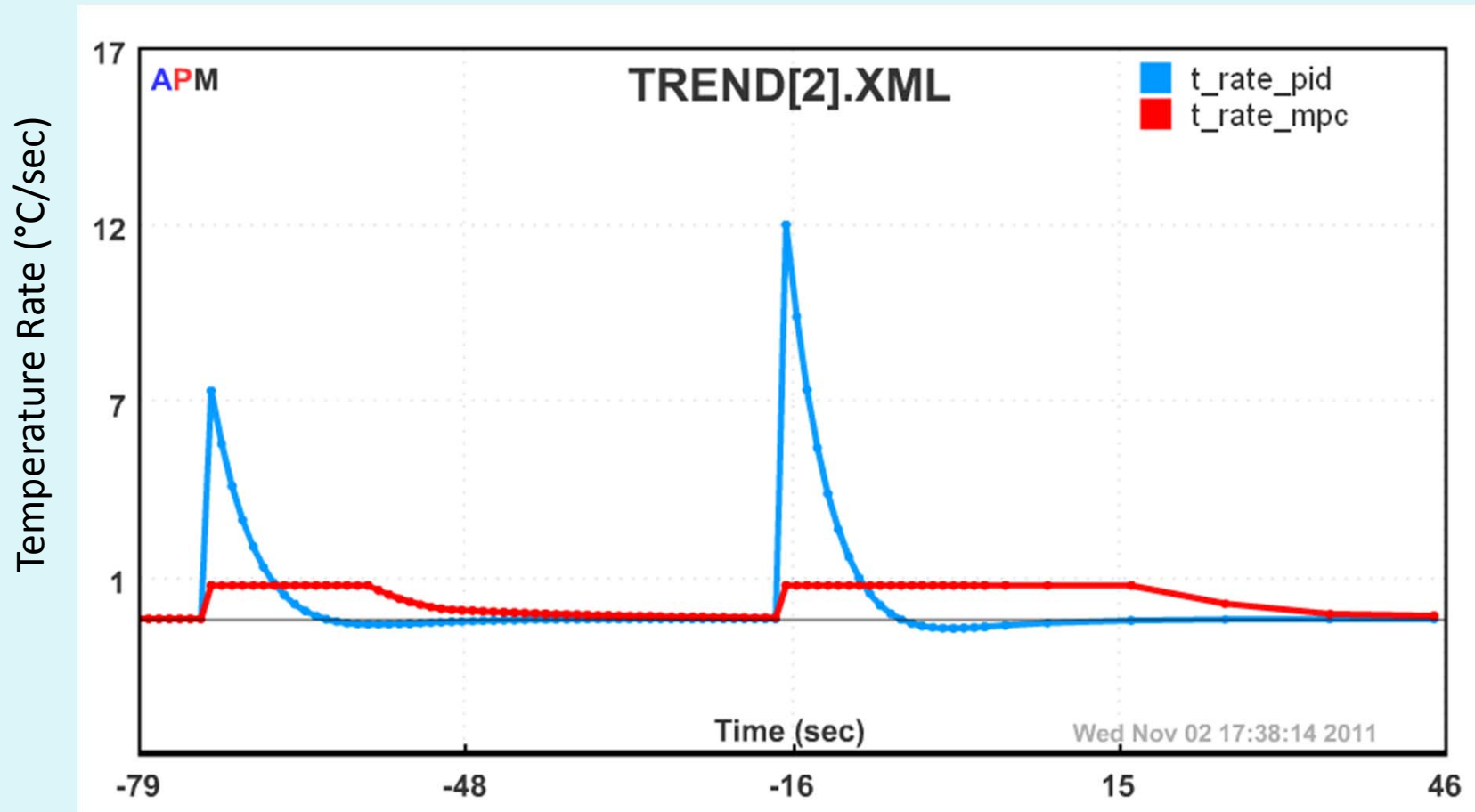
# Model Predictive Control



# Operate Within Constraints



# Rate of Change for PID and MPC



# Recommendations

- ◆ Model Predictive Control has advantages for:
  - ◆ Start-up
  - ◆ Large load changes
  - ◆ Constrained control - MV or CV tuning
- ◆ Start control studies now with FOPDT model
  - ◆ Interface with PLC through OPC connection to RS Linx
  - ◆ Existing equipment sufficient
- ◆ Address complex modeling / control issues
  - ◆ Seek funding for a graduate student
  - ◆ Investigate multi-variable control

